

Best presentations in session**ACC2014****Friday, June 6**

10:40-11:00 FrA01.3

System Identification of the Green Bank Telescope Structure and Servo System, pp. 3704-3709.

Ranka, Trupti	Case Western Res. Univ.
Garcia-Sanz, Mario	Case Western Res. Univ.
Weadon, Timothy	National Radio Astronomy Observatory
Ford, John	National Radio Astronomy Observatory

10:00-10:20 FrA02.1

Importance of Lidar Measurement Timing Accuracy for Wind Turbine Control (I), pp. 3728-3733.

Dunne, Fiona	Univ. of Colorado Boulder
Pao, Lucy Y.	Univ. of Colorado Boulder
Schlipf, David	Stuttgart Wind Energy, Univ. of Stuttgart
Scholbrock, Andrew	National Renewable Energy Lab.

10:00-10:20 FrA03.1

Estimation of Linear Parameter-Varying Affine State Space Models Using Synchronised Periodic Input and Scheduling Signals (I), pp. 3766-3771.

Goos, Jan	Vrije Univ. Brussel
Lataire, John	Vrije Univ. Brussel
Pintelton, Rik M.	Vrije Univ. Brussel

10:40-11:00 FrA04.3

A Norm Optimal Iterative Learning Control Framework towards Internet-Distributed Hardware-In-The-Loop Simulation, pp. 3814-3819.

Ge, Xinyi	Univ. of Michigan
Brudnak, Mark	TARDEC
Stein, Jeffrey L.	Univ. of Michigan
Ersal, Tulga	Univ. of Michigan

10:20-10:40 FrA05.2

Optimal Power Management for a Series Hybrid Electric Vehicle Cognizant of Battery Mechanical Effects, pp. 3844-3849.

Kim, Youngki	Univ. of Michigan
Mohan, Shankar	Univ. of Michigan
Samad, Nassim	Univ. of Michigan
Siegel, Jason B.	Univ. of Michigan
Stefanopoulou, Anna G.	Univ. of Michigan

10:00-10:20 FrA06.1

Distributed Formation Control without a Global Reference Frame, pp. 3874-3879.

Montijano, Eduardo	Centro Univ. de la Defensa
Zhou, Dingjiang	Boston Univ.
Schwager, Mac	Boston Univ.
Sagues, Carlos	Univ. de Zaragoza

11:20-11:40 FrA07.5

Low Friction Emulation of Lateral Vehicle Dynamics Using Four-Wheel Steer-By-Wire (I), pp. 3936-3941.

Russell, Holly	Stanford Univ.
Gerdes, J. Christian	Stanford Univ.

10:40-11:00 FrA08.3

Single-Integration Mode Scheduling for Linear Time-Varying Switched Systems, pp. 3960-3965.

Mavrommati, Anastasia	Northwestern Univ.
Murphrey, Todd	Northwestern Univ.

10:40-11:00 FrA09.3

Stabilization and Destabilization of Network Processes by Sparse Remote Feedback: Graph-Theoretic

<i>Approach</i> , pp. 3996-4001.		
Abad Torres, Jackeline	Washington State Univ.	
Roy, Sandip	Washington State Univ.	
11:40-12:00		FrA10.6
<i>Planning End Effector Trajectories for a Serially Linked, Floating-Base Robot with Changing Support Polygon</i> , pp. 4050-4055.		
Cappo, Ellen	Carnegie Mellon Univ.	
Choset, Howie	Carnegie Mellon Univ.	
10:00-10:20		FrA11.1
<i>Fluid Flow Control Applications of H2 Optimal Actuator and Sensor Placement (I)</i> , pp. 4056-4061.		
Chen, Kevin K.	Princeton Univ.	
Rowley, Clarence W.	Princeton Univ.	
11:00-11:20		FrA12.4
<i>Quadratic Program Based Control of Fully-Actuated Transfemoral Prosthesis for Flat-Ground and Up-Slope Locomotion (I)</i> , pp. 4113-4119.		
Zhao, Huihua	Texas A&M Univ.	
Ames, Aaron	Texas A&M Univ.	
11:20-11:40		FrA13.5
<i>Design and Validation of an Extended Kalman Filter for Estimating Hemodynamic Variables</i> , pp. 4157-4162.		
Luspay, Tamás	Univ. of Houston	
Grigoriadis, Karolos M.	Univ. of Houston	
11:40-12:00		FrA14.6
<i>A New Tracking Controller for Neuromuscular Electrical Stimulation under Input Delays: Case Study in Prediction</i> , pp. 4198-4203.		
Karafyllis, Iasson	National Tech. Univ. of Athens	
Malisoff, Michael	Louisiana State Univ.	
de Queiroz, Marcio	Louisiana State Univ.	
Krstic, Miroslav	Univ. of California, San Diego	
Yang, Ruzhou	Louisiana State Univ.	
10:00-10:20		FrA15.1
<i>Improved State Dependent Parametrizations Including a Piecewise Linear Feedback for Constrained Linear MPC</i> , pp. 4204-4209.		
Goebel, Gregor	Univ. of Stuttgart	
Allgöwer, Frank	Univ. of Stuttgart	
10:20-10:40		FrA16.2
<i>Control of Magnetic Bearings with Plug-In Time-Varying Harmonic Resonators (I)</i> , pp. 4249-4254.		
Kang, Christopher	Univ. of California, Los Angeles	
Tsao, Tsu-Chin	Univ. of California, Los Angeles	
11:20-11:40		FrA17.5
<i>Conic-Sector-Based Controller Synthesis: Theory and Experiments</i> , pp. 4304-4309.		
Bridgeman, Leila Jasmine	McGill Univ.	
Caverly, Ryan James	Univ. of Michigan	
Forbes, James Richard	Univ. of Michigan	
11:00-11:20		FrA18.4
<i>Alternating Direction Method of Multipliers for Strictly Convex Quadratic Programs: Optimal Parameter Selection</i> , pp. 4336-4341.		
Raghunathan, Arvind	Mitsubishi Electric Res. Lab.	
Di Cairano, Stefano	Mitsubishi Electric Res. Lab.	
10:40-11:00		FrA19.3

<i>Utilization of Blade Pitch Control in Low Wind Speed for Floating Offshore Wind Turbines</i> , pp. 4366-4371.	
Bagherieh, Omid	Univ. of California, Berkeley
Nagamune, Ryozo	Univ. of British Columbia
14:50-15:10	FrB01.5
<i>Two-Step System Identification for Control of Small UAVs Along Pre-Specified Trajectories</i> , pp. 4416-4421.	
Grymin, David	Air Force Res. Lab.
Farhood, Mazen	Virginia Tech.
14:30-14:50	FrB02.4
<i>Nonlinear Model Predictive Control of Floating Wind Turbines with Individual Pitch Control (I)</i> , pp. 4446-4451.	
Raach, Steffen	Univ. of Stuttgart
Schlipf, David	Stuttgart Wind Energy, Univ. of Stuttgart
Sandner, Frank	Univ. of Stuttgart, SWE
Matha, Denis	Univ. of Stuttgart
Cheng, Po Wen	Stuttgart Wind Energy, Univ. of Stuttgart
14:50-15:10	FrB03.5
<i>Robustness Analysis of Linear Parameter Varying Systems Using Integral Quadratic Constraints (I)</i> , pp. 4488-4493.	
Pfifer, Harald	Univ. of Minnesota
Seiler, Peter	Univ. of Minnesota
15:10-15:30	FrB04.6
<i>On a Recurrence Principle for a Class of Stochastic Hybrid Systems</i> , pp. 4530-4535.	
Teel, Andrew R.	Univ. of California at Santa Barbara
14:30-14:50	FrB05.4
<i>A Feedback Linearization Controller for Trajectory Tracking of the Furuta Pendulum</i> , pp. 4555-4560.	
Aguilar-Avelar, Carlos	CITEDI-IPN
Moreno-Valenzuela, Javier	CITEDI-IPN
14:10-14:30	FrB06.3
<i>Robust Data Map Design Using Chance Constrained Optimization</i> , pp. 4585-4592.	
Laftchiev, Emil	The Pennsylvania State Univ.
Lagoa, Constantino M.	Pennsylvania State Univ.
Brennan, Sean	The Pennsylvania State Univ.
14:50-15:10	FrB07.5
<i>Stability Analysis of Connected Cruise Control with Stochastic Delays (I)</i> , pp. 4636-4641.	
Qin, Wubing B.	Univ. of Michigan
Gomez, Marcella M.	California Inst. of Tech.
Orosz, Gabor	Univ. of Michigan
13:50-14:10	FrB09.2
<i>Affinity-Based Distributed Algorithm for 3D Reconstruction in Large Scale Visual Sensor Networks</i> , pp. 4683-4688.	
Masiero, Andrea	Univ. di Padova
Cenedese, Angelo	Univ. of Padova
13:30-13:50	FrB10.1
<i>Observability Based Control in Range-Only Underwater Vehicle Localization</i> , pp. 4714-4719.	
Quenzer, Jake	Univ. of Washington
Morgansen, Kristi A.	Univ. of Washington
15:10-15:30	FrB11.6

Modeling, Identification and Feedforward Control of Multivariable Hysteresis by Combining Bouc-Wen Equations and the Inverse Multiplicative Structure (I), pp. 4783-4789.

Habineza, Didace	FEMTO-ST Inst.
Rakotondrabe, Micky	FEMTO-ST Inst.
Le Gorrec, Yann	ENSM, FEMTO-ST / AS2M

13:50-14:10 FrB12.2

Task-Relevant Adaptation of Musculoskeletal Impedance During Posture and Movement (I), pp. 4796-4801.

Ludvig, Daniel	Rehabilitation Inst. of Chicago
Perreault, Eric	Northwestern Univ.

13:30-13:50 FrB13.1

A Dynamic State Observer for Real-Time Reconstruction of the Tokamak Plasma Profile State and Disturbances, pp. 4828-4835.

Felici, Federico	Eindhoven Univ. of Tech.
De Baar, Marco	FOM
Steinbuch, Maarten	Eindhoven Univ. of Tech.

13:30-13:50 FrB14.1

Stabilization of Time-Varying Nonlinear Systems with Time Delays Using a Trajectory Based Approach, pp. 4866-4870.

Mazenc, Frederic	EPI INRIA DISCO
Malisoff, Michael	Louisiana State Univ.

14:50-15:10 FrB15.5

Robust Nonlinear Predictive Control for Autonomous Ground Vehicles, pp. 4925-4930.

Gao, Yiqi	Univ. of California, Berkeley
Gray, Andrew	Univ. of California, Berkeley
Carvalho, Ashwin	Univ. of California, Berkeley
Tseng, Eric	Ford Motor Company
Borrelli, Francesco	University of California at Berkeley

14:30-14:50 FrB16.4

On the Distance to Optimality of the Geometric Approximate Minimum-Energy Attitude Filter (I), pp. 4955-4960.

Zamani, Mohammad	The Univ. of New South Wales ADFA
Trumpf, Jochen	Australian National Univ.
Mahony, Robert	Australian National Univ.

14:10-14:30 FrB17.3

Robust Stability Analysis of Discrete-Time Linear Systems Characterized by Stochastic Polytopes, pp. 4985-4990.

Hosoe, Yohei	Kyoto Univ.
Hagiwara, Tomomichi	Kyoto Univ.

14:10-14:30 FrB18.3

Periodic and Event-Triggered Communication for Distributed Continuous-Time Convex Optimization, pp. 5022-5027.

Kia, Solmaz	Univ. of California at San Diego (UCSD)
Cortes, Jorge	Univ. of California, San Diego
Martinez, Sonia	Univ. of California at San Diego

13:50-14:10 FrB19.2

Operation of Residential Hybrid Renewable Energy Systems: Integrating Forecasting, Optimization and Demand Response, pp. 5055-5060.

Wang, Xiaonan	Univ. of California, Davis
Palazoglu, Ahmet N.	Univ. of California at Davis
EI-Farra, Nael H.	Univ. of California, Davis

16:20-16:40	FrC01.2
<i>Unscented Statistical Linearization and Robustified Kalman Filter for Nonlinear Systems with Parameter Uncertainties</i> , pp. 5091-5096.	
Murata, Masaya	NTT Communication Science Lab. NTT Corp.
Nagano, Hidehisa	NTT Communication Science Lab. NTT Corp.
Kashino, Kunio	NTT Communication Science Lab. NTT Corp.
17:00-17:20	FrC02.4
<i>Step Size Analysis in Discrete-Time Dynamic Average Consensus</i> , pp. 5139-5144.	
Montijano, Eduardo	Centro Univ. de la Defensa
Montijano, Juan Ignacio	Univ. of Zaragoza
Sagues, Carlos	Univ. de Zaragoza
Martinez, Sonia	Univ. of California at San Diego
16:40-17:00	FrC03.3
<i>Control of Heterogeneous Groups of LPV Systems Interconnected through Directed and Switching Topologies</i> , pp. 5168-5173.	
Hoffmann, Christian	Hamburg Univ. of Tech.
Eichler, Annika	Hamburg Univ. of Tech. (TUHH)
Werner, Herbert	Hamburg Univ. of Tech.
16:20-16:40	FrC04.2
<i>Adaptive Splitting Technique for Gaussian Mixture Models to Solve Kolmogorov Equation</i> , pp. 5198-5203.	
Vishwajeet, Kumar	Univ. at Buffalo
Singla, Puneet	Univ. at Buffalo
17:00-17:20	FrC05.4
<i>A Robust Adaptive Controller for Surface-Mount Permanent Magnet Synchronous Machines</i> , pp. 5248-5253.	
Reed, David	Univ. of Michigan
Sun, Jing	Univ. of Michigan
Hofmann, Heath	Univ. of Michigan
16:40-17:00	FrC06.3
<i>Finite-Time Distributed Averaging</i> , pp. 5272-5275.	
Mou, Shaoshuai	Yale Univ.
Morse, A. Stephen	Yale Univ.
17:40-18:00	FrC07.6
<i>Sensor Fusion for Unmanned Aircraft System Navigation in an Urban Environment</i> , pp. 5325-5330.	
Rufa, Justin	Univ. of Michigan
Atkins, Ella	Univ. of Michigan
16:00-16:20	FrC08.1
<i>Observer Design for Linear Multi-Rate Sampled-Data Systems</i> , pp. 5331-5336.	
Moarref, Miad	Concordia Univ.
Rodrigues, Luis	Concordia Univ.
17:40-18:00	FrC09.6
<i>Fast Convergence for Time-Varying Semi-Anonymous Potential Games</i> , pp. 5396-5401.	
Borowski, Holly	Univ. of Colorado Boulder
Marden, Jason	Univ. of Colorado at Boulder
16:40-17:00	FrC10.3
<i>Statistical Mechanics-Inspired Framework for Studying the Effects of Mixed Traffic Flows on Highway Congestion</i> , pp. 5414-5419.	
Jerath, Kshitij	The Pennsylvania State Univ.
Ray, Asok	Pennsylvania State Univ.
Brennan, Sean	The Pennsylvania State Univ.

Gayah, Vikash	Pennsylvania State Univ.
17:20-17:40	FrC11.5
<i>A Distributed PID Controller for Network Congestion Control Problems</i> , pp. 5465-5470.	
Zhang, Xuan	Univ. of Oxford
Papachristodoulou, Antonis	Univ. of Oxford
17:40-18:00	FrC12.6
<i>Nonlinear Dynamics in Closed-Loop Anesthesia: Pharmacokinetic/Pharmacodynamic Model under PID-Feedback</i> , pp. 5508-5513.	
Zhusubaliyev, Zhanybai	South West State Univ. (Kursk State Tech. Univ.)
Medvedev, Alexander V.	Uppsala Univ.
Silva, Margarida M.	Uppsala Univ.
16:20-16:40	FrC13.2
<i>Detection & Estimation Algorithms for In-Pipe Leak Detection</i> , pp. 5520-5526.	
Chatzigeorgiou, Dimitris	MIT
Youcef-Toumi, Kamal	Massachusetts Inst. of Tech.
Ben-Mansour, Rached	King Fahd Univ. of Petroleum & Minerals
17:40-18:00	FrC14.6
<i>Time-Delayed Vision-Based DC Motor Control Via Rightmost Eigenvalue Assignment</i> , pp. 5576-5581.	
Yi, Sun	North Carolina A&T State Univ.
Ulsoy, A. Galip	Univ. of Michigan
17:20-17:40	FrC15.5
<i>Stabilization of Nonlinear Sampled-Data Systems and Economic Model Predictive Control Application</i> , pp. 5606-5613.	
Ellis, Matthew	Univ. of California, Los Angeles
Karafyllis, Iasson	National Tech. Univ. of Athens
Christofides, Panagiotis D.	Univ. of California at Los Angeles
17:40-18:00	FrC16.6
<i>A Minmax Extremum-Seeking Control Design Technique</i> , pp. 5651-5656.	
Guay, Martin	Queen's Univ.
Dochain, Denis	Univ. Catholique de Louvain
16:00-16:20	FrC17.1
<i>Performance Optimization Over Positive L_infty Cones</i> , pp. 5657-5662.	
Naghnaeian, Mohammad	Univ. of Illinois Urbana-Champaign
Voulgaris, Petros G.	Univ. of Illinois, Urbana-Champaign
16:40-17:00	FrC18.3
<i>Nonlinear Measurement Update for Estimation of Angular Systems Based on Circular Distributions</i> , pp. 5706-5711.	
Kurz, Gerhard	Karlsruhe Inst. of Tech. (KIT)
Gilitshenski, Igor	Karlsruhe Inst. of Tech. (KIT)
Hanebeck, Uwe D.	Karlsruhe Inst. of Tech. (KIT)
17:20-17:40	FrC19.5
<i>Computing Optimal Control Laws for Finite Stochastic Systems with Non-Classical Information Patterns</i> , pp. 5754-5759.	
Uribe, César A.	Univ. of Illinois at Urbana-Champaign
Keviczky, Tamas	Delft Univ. of Tech.
van Schuppen, Jan H.	Van Schuppen Control Res.